

Data Sheet ROTAX[®] Rxhq 110-50T1.5

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Hollow Shaft Motor ROTAX[®] Rxhq = high torque



Highlights

Compact direct drive with high torque up to 4.0Nm (35.40 lbf·in)

Flexible positioning with a repeatability of ± 1arcsec

Single-turn absolute encoder

Large hollow shaft with a diameter of 50mm (1.97")

No wear and tear, the direct drive ensures maximum precision over the entire service life

Variable one-cable connection to XENAX[®] in 180° grid orientation

Torque limitation and torque monitoring with XENAX[®] servo controller



General

The direct drive developed in-house impresses with its flat design, compact external dimensions and a hollow shaft with a diameter of 50mm. Cables, vacuum or compressed air lines, light and laser beams, glass fibers or camera lenses can thus be easily guided through the hollow shaft.

The absolute measuring system allows an immediate start without previous referencing. With a resolution of 120'000, 648'000 or 2'592'000inc. per revolution, repeatability of ± 1arcsec can be achieved. The single-cable connection can be supplied in right-hand or left-hand output configuration.

Together with the patented "Force Calibration" function, undesired cogging, weight and friction forces of the ROTAX® Rxhq direct drives can be easily compensated. This makes it possible to specify, limit and monitor torques in processes. Together with the Forceteq® basic technology included in the XENAX® servo controller, complete torque/distance diagrams can be recorded - an additional torque sensor is not necessary.

> Alois Jenny Jenny Science AG



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1 Dimension ROTAX[®] Rxhq 110-50T1.5

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1.1 Installation dimension



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1.2.2 Centering rings



1.2.3 Hole pattern for direct assembly





1.3 Installation options

1.3.1 Installation rear side with distance sleeves



Pos.	QTY	Designation
1	4	Fixing screws M4 (max. tightening torque 2.9Nm (25lbf·in))
2	1	ROTAX [®] Rxhq 110-50T1.5
3	4	Centering rings (Ø8 g6 x 1.5)
4	1	Mounting plate customer



1.3.2 Installation flange side with centering ring





Pos.	QTY	Designation
1	1	Mounting plate, customer – Flange side
2	4	Centering ring (Ø8 g6 x 1.5)
3	1	ROTAX [®] Rxhq 110-50T1.5
4	1	Fixing screws M4 (max. tightening torque 2.9Nm (25/bf·in))



2 Smart Praxis Oriented Details

2.1 Hollow shaft diameter 50mm (1.97")



The large hollow shaft with a diameter of 50mm (1.97") offers generous space for cables, vacuum or compressed air lines, light and laser beams, glass fibres and other media.

2.2 Single-Turn Absolut Encoder



Thanks to the integrated absolute encoder with a resolution of 120'000 inc. per revolution, repeatability of ± 11arcsec can be achieved. The optical measuring systems with 648'000 inc. and 2'592'000 inc. then achieve ± 4 arcsec resp. ± 1 arcsec repeatability.

Due to the absolute position, the ROTAX[®] Rxhq is immediately ready for operation after power-on, no reference drive is necessary.

2.3 Torque limitation and torque measurement



The patented function "Force Calibration" is able to compensate the magnetic cogging forces, the load and the friction forces of the Rotax[®] direct drive in a very simple way. This is how it becomes possible to limit and monitor torques in process. Together with the XENAX[®] servo controller, complete torque/displacement diagrams can also be recorded - an additional sensor is not necessary.



2.4 One-Cable connection reduces cabling requirements



The one-cable connection from Jenny Science simplifies the whole machine cabling complexity. In addition, the cable chains are more compact and lighter, need less room and achieve higher dynamics.

2.5 Cabel connection 180° pattern



The cable connection can be selected to the right, left and downwards. The corresponding article number must be specified when ordering. The cable outlet cannot be turned by yourself.



3 Performance data

3.1 Techniscal specification

Supply voltage				24V DC	48V DC
Nominal speed ⁽¹⁾ 120`000 Inc.	n _N	rpm		300	600
Nominal speed ⁽¹⁾ 648`000 Inc.	n _N	rpm		300	600
Nominal speed ⁽¹⁾ 2`592`000 Inc.	n _N	rpm		200	200
Stall torque	M_0	Nm	(lbf∙in)	1.6 (14.16)	1.6 (14.16)
Nominal torque ⁽¹⁾	M_{N}	Nm	(lbf∙in)	1.5 (13.28)	1.5 (13.28)
Peak torque ⁽²⁾	М _Р	Nm	(lbf∙in)	4.0 (35.40)	4.0 (35.40)
Nominal current ⁽¹⁾	I _N	А		4.0	4.0
Peak current ⁽²⁾	Ι _Ρ	А		12.0	12.0
Mechanical Data					
Max. axial load		Ν	(lbf)	10'000 (22	248.0)
Max. moment load		Nm	(lbf∙in)	250 (22	212.7)
Rotor moment of inertia	J _{Rot}	g·cm²	(lbf·in²)	4'800 (1.	6402)
Total weight	m	g	(lbs)	1'200 (2.	6500)

(1) continuous operation with $25C^{\circ}(77^{\circ}F)$ ambient temperature and convection cooling (ambient air)

(2) peak operation (duty 10%)



3.2 Torque/Speed curve

Nominal operation	Continous operation	Peak operation

Supply voltage Us = 24VDC (120'000Inc. encoder)



Supply voltage Us = 48VDC (120'000Inc. encoder)





120`000 Inc., Vmax 600 rpm

648`000 Ink., Vmax 600 rpm

2'592`000 Ink., Vmax 200 rpm

4 Accuracy

± 11 arcsec

± 4 arcsec

± 1 arcsec

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Standard	reso	lution	pol	lring	
Bi-direct	tional	repea	tab	oility	

Optional optical resolution Bi-directional repeatability

Optional optical resolution Bi-directional repeatability

Reference drive

Zero point absolut



With the single-turn absolute encoder the position is available immediately after poweron. Therefore, no reference drive is necessary. For the alignment of the rotor flange, a single bore Ø4H6 with aligned marking on the shaft and a marking on the symmetry axis of the housing is provided. The absolute zero point is in straight alignment of the two markings.

4.2 Mechanical accuracy

Runout [μm]	The ROTAX [®] Rxhq is delivered with the following tolerances as standard. (Smaller tolerances are possible by selection individual motors from serial production i.E <5μm)
Runout radial on Ø54H7	<10µm
Runout axial on Ø94	<10µm



5 Maintenance, Life time

5.1 Lubrication

The double row angular contact ball bearing of the ROTAX[®] Rxhq is maintenance-free and cannot be relubricated.

5.2 Life time

The ROTAX[®] Rxhq is a direct drive. This means no wear and tear and therefore highest precision over the whole lifetime.

Basically, the preloaded double row angular contact ball bearing is the life-determining element.

Actions with which life time can be extended:

- Trajectories with curve profiles instead of trapezoidal profiles (XENAX[®] Servo controller, default value S-curve profile = 20%).
- Dynamics not higher than needed.
- Completing non cycle time critical motions slower.
- Avoid pollution in the guides.



6 Safety, Environment
6.1 Safety with XENAX [®] Servo Controller
EMC Immunity Testing, Industrial Class A
Immunity for Functional Safety Functional safety of power drive systems Electrostatic discharges ESD, Electromagnetic Fields, Fast electric transients Bursts, radio frequency common
mode
EMIC Emissions Testing, Residential Class B
Radiated EM Field, Interference voltage Functional safety of power drive systems

6.1 Environmental Conditions

Storage and transport	No outdoor storage. Storage rooms have to be well vented and dry. Storage temperature -25°C up to +55°C (-13°F up to 131°F).
Operational temperature	5°C - 50°C (41°F - 122°F) Environment, reduction in performance at 40°C (104°F).
Operational humidity Cooling	10-90% non-condensing. No need of external cooling. The mechanical mounting to a flange allows additional heat dissipation thanks to thermal conduction. This allows a higher performance.
Protection category	IP 40



7 Note

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Information in this instruction manual is subject to Modifications.

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